



MPI Quiz





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What is MPI?

- A the Message-Passing Interface
- B the Miami Police Investigators
- C the Minimal Polynomial Instantiation
- D the Millipede Podiatry Institution
- E a way of doing distributed-memory parallel programming

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To compile and run an MPI program requires

- A special compilers
- B special libraries
- C a special parallel computer
- D a special operating system

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After initiating an MPI program with "mpirun -n 4 ./mympiprogram", what does the call to MPI_Init do?

- A create the 4 parallel processes
- B start program execution
- C enable the 4 independent programs subsequently to communicate with each other
- D create the 4 parallel threads

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If you call MPI_Recv and there is no incoming message, what happens?

- A the Recv fails with an error
- B the Recv reports that there is no incoming message
- C the Recv waits until a message arrives (potentially waiting forever)
- D the Recv times out after some system-specified delay (e.g. a few minutes)

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If you call MPI synchronous send (MPI_Ssend) and there is no receive posted

- A the message disappears
- B the send fails
- C the send waits until a receive is posted (potentially waiting forever)
- D the message is stored and delivered later on (if possible)
- E the send times out after some system-specified delay (e.g. a few minutes)

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If you call MPI asynchronous send (MPI_Bsend - buffered send) and there is no receive posted

- A the message disappears
- B the send fails
- C the send waits until a receive is posted (potentially waiting forever)
- D the message is stored and delivered later on (if possible)
- E the send times out after some system-specified delay (e.g. a few minutes)
- F the sending process continues execution regardless of whether the message is received

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If you call a standard send (MPI_Send) and there is no matching receive, which of the following are possible outcomes?

- A the message disappears
- B the send fails
- C the send waits until a receive is posted (potentially waiting forever)
- D the message is stored and delivered later on (if possible)
- E the send times out after some system-specified delay (e.g. a few minutes)
- F the program continues execution regardless of whether the message is received

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The MPI receive routine has a parameter "count" - what does this mean?

- A the size of the incoming message (in bytes)
- B the size of the incoming message (in items, e.g. integers)
- C the size you have reserved for storing the message (in bytes)
- D the size you have reserved for storing the message (in items, e.g. integers)

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What happens if the incoming message is larger than "count" ?

- A the receive fails with an error
- B the receive reports zero data received
- C the message writes beyond the end of the available storage
- D only the first "count" items are received

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What happens if the incoming message (of size "n") is smaller than "count"

- A the receive fails with an error
- B the receive reports zero data received
- C the first "n" items are received
- D the first "n" items are received and the rest of the storage is zeroed

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How is the actual size of the incoming message reported?

- A the value of "count" in the receive is updated
- B MPI cannot tell you
- C it is stored in the Status parameter
- D via the associated tag

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Consider the following (pseudo) code - remember that Ssend means Synchronous Send. What happens at runtime?

Process A

```
MPI_Ssend(sendmsg1, B, tag=1)
```

```
MPI_Ssend(sendmsg2, B, tag=2)
```

Process B

```
MPI_Recv(recvmsg2, A, tag=2)
```

```
MPI_Recv(recvmsg1, A, tag=1)
```

- A The code is guaranteed to deadlock
- B The code might deadlock
- C `recvmsg1 = sendmsg1` and `recvmsg2 = sendmsg2`
- D `recvmsg1 = sendmsg2` and `recvmsg2 = sendmsg1`
- E both receives complete but their contents are undefined

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Consider the following (pseudo) code - remember that lsend is a non-blocking / immediate send which means that the program always continues execution to the next line. What happens at runtime?

It is most useful to consider the case where Process A is running ahead of B, i.e. the sends are all posted in advance of the receives.

(if you prefer you can consider using Bsend - i.e. buffered / asynchronous send - as the answer will be the same).

Process A

```
MPI_Isend(sendmsg1, B, tag=1)
MPI_Isend(sendmsg2, B, tag=1)
```

Process B

```
MPI_Recv(recvmsg1, A, tag=1)
MPI_Recv(recvmsg2, A, tag=1)
```

- A The code is guaranteed to deadlock
- B The code might deadlock
- C recvmsg1 = sendmsg1 and recvmsg2 = sendmsg2
- D recvmsg1 = sendmsg2 and recvmsg2 = sendmsg1
- E both receives complete but their contents are undefined



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Consider the following (pseudo) code - remember that lsend is a non-blocking / immediate send. What happens at runtime?

Process A

```
MPI_Isend(sendmsg1, B, tag=1)
MPI_Isend(sendmsg2, B, tag=2)
```

Process B

```
MPI_Recv(recvmsg2, A, tag=2)
MPI_Recv(recvmsg1, A, tag=1)
```

- A The code is guaranteed to deadlock
- B The code might deadlock
- C recvmsg1 = sendmsg1 and recvmsg2 = sendmsg2
- D recvmsg1 = sendmsg2 and recvmsg2 = sendmsg1
- E both receives complete but their contents are undefined

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Consider the following (pseudo) code - remember that `I`send is a non-blocking / immediate send. What happens at runtime?

Process A

```
MPI_Isend(sendmsg1, B, tag=1)
```

```
MPI_Isend(sendmsg2, B, tag=2)
```

Process B

```
MPI_Recv(recvmsg1, A, tag=MPI_ANY_TAG)
```

```
MPI_Recv(recvmsg2, A, tag=MPI_ANY_TAG)
```

- A The code is guaranteed to deadlock
- B The code might deadlock
- C `recvmsg1 = sendmsg1` and `recvmsg2 = sendmsg2`
- D `recvmsg1 = sendmsg2` and `recvmsg2 = sendmsg1`
- E both receives complete but their contents are undefined

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Consider the following (pseudo) code - remember that `Irecv` is a non-blocking / immediate send. What happens at runtime?

Note that the code is written so that the time ordering in which the MPI functions are called is guaranteed to be: Send on A; Send on B; Recv on C.

Process A

```
MPI_Isend(sendmsgA, C)
MPI_Barrier()
```

Process B

```
MPI_Barrier()
MPI_Isend(sendmsgB, C)
```

Process C

```
MPI_Barrier()
MPI_Recv(recvmsgA, source=MPI_ANY_SOURCE)
MPI_Recv(recvmsgB, source=MPI_ANY_SOURCE)
```

A The code is guaranteed to deadlock

B The code might deadlock

MPI_Isend(sendmsgA, C)
MPI_Barrier()

Process B

MPI_Barrier()
MPI_Isend(sendmsgB, C)

Process C

MPI_Barrier()
MPI_Recv(recvmsgA, source=MPI_ANY_SOURCE)
MPI_Recv(recvmsgB, source=MPI_ANY_SOURCE)

- A The code is guaranteed to deadlock
- B The code might deadlock
- C recvmsgA = sendmsgA and recvmsgB = sendmsgB
- D recvmsgA = sendmsgB and recvmsgB = sendmsgA
- E both receives complete but their contents are undefined

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Consider the following (pseudo) code - remember that `lsend` is a non-blocking / immediate send.

Which of the following are possible outcomes where we send 10 integers and receive 10 real numbers?

Process A

```
MPI_Send(B, sendmsg1, 10, MPI_INT)
```

Process B

```
MPI_Recv(A, recvmsg1, 10, MPI_FLOAT)
```

- A The call is erroneous so MPI reports an error
- B The integers are converted to floats and stored in `recvmsg1`
- C The message is not delivered as the send and receive do not match, and the program continues
- D The message is delivered but the contents of `recvmsg1` are potentially garbage
- E The send does not match the receive, so the receive keeps waiting for a message of type `MPI_INT`

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Some MPI collective calls specify both a send type and a receive type, e.g. `MPI_Scatter(sendbuf, sendcount, sendtype, recvbuf, recvcount, recvtype, ...)`.

However, the vast majority of times you see this call used in practice we have `sendtype = recvtype` (and also `sendcount=recvcount`).

Why does MPI make you specify both types?

- A So it can check at runtime that you haven't made a silly mistake
- B So it can do type conversion (e.g integer -> float) if required
- C The types and counts can be different provided that at least one of them is an MPI derived type
- D The types and counts can be different provided that the two buffers are the same length in bytes

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What is the output of this MPI code on 8 processes, i.e. on running ranks 0, 1, 2, 3, 4, 5, 6 and 7?

```
if (rank % 2 == 0) // Even processes
{
  MPI_Allreduce(&rank, &evensum, 1, MPI_INT, MPI_SUM, MPI_COMM_WORLD);
  if (rank == 0) printf("evensum = %d\n", evensum);
}
else // Odd processes
{
  MPI_Allreduce(&rank, &oddsum, 1, MPI_INT, MPI_SUM, MPI_COMM_WORLD);
  if (rank == 1) printf("oddsum = %d\n", oddsum);
}
```

- A evensum = 16, oddsum = 12
- B evensum = 28, oddsum = 28
- C evensum = 12, oddsum = 16
- D evensum = 6, oddsum = 22

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You receive an MPI program from a colleague and see that it has a large number of calls to `MPI_Barrier()`. Which of these are plausible explanations (assuming the program uses relatively standard two-sided MPI functionality and doesn't push the boundaries of the standard)

- A The barriers are required to ensure consistent timing of various parallel operations, but have no impact on program correctness
- B The barriers are required for program correctness as it uses lots of non-blocking operations
- C The barriers are unnecessary and can safely be removed if the program is otherwise correct
- D The barriers are required to ensure that subsequent collective operations can be called safely

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Was this tutorial useful?

True

False

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The End

